

CR-15iA



Max. load capacity at wrist: 15 kg



Max. reach: 1441 mm

FANUC

| Robot | | | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | Maximum speed (°/s) | | | | | | Average Power consumption (kW) | Protection | | | | |
|--------|---------|------|----------------------------------|------------|-----------------|--------------------|------------------------|------------------|-----|-----|-----|-----|-----|---------------------|------|------|------|------|------|--------------------------------|--------------------|--------------------|--------------------|---------------|----------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | J1 | J2 | J3 | J4 | J5 | J6 | | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Body standard | Wrist & J3 arm |
| CR | iA | 15 | 15 | 1441 | 6 | ±0.02** | 255 | 340/ 370*** | 180 | 312 | 380 | 280 | 900 | 800* | 800* | 800* | 800* | 800* | 800* | 26/ 0.9 | 26/ 0.9 | 11/ 0.3 | 1 | IP54 | IP67 |

● standard ○ on request - not available * max. cartesian speed 800mm/sec (1500mm/sec. when safety monitored) ** Based on ISO9283 ***Option

CR-15iA

Hollow wrist



CR-15iA

