

CRX-10iA



Max. load capacity
at wrist: 10 kg



Max. reach
(end of flange):
1249 mm

FANUC

Robot			Max load capacity at wrist (kg)	***Reach (mm)	Controlled axes	**Repeatability (mm)	Mechanical weight (kg)	Motion range [°]						*Maximum speed (mm/s)		***Allowable Wrist Load			Input power source (VAC)	Protection	
Series	Version	Type						J1	J2	J3	J4	J5	J6	Collaborative Mode	High Speed Mode	J4 Moment/ Inertia	J5 Moment/ Inertia	J6 Moment/ Inertia		Body standard	Wrist & J3 arm
CRX	iA	10	10	1249	6	± 0.04	40	380	360	570	380	360	450	1000	2000	34.8/ 1.28	26/ 0.9	11/ 0.3	100-120 200-240	IP67	IP67

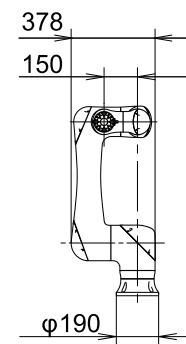
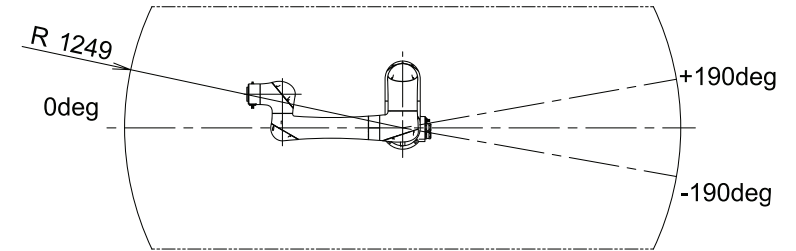
● standard ○ on request - not available * During short distance, it may not reach the maximum value stated. Please set motion speed according to risk assessment of system. ** Based on ISO9283 ***Nm/Kg.m² ****At the end of flange

CRX-10iA

Standard model



CRX-10iA



Operating Space
of End of Flange
(J4 +90 deg.)

